# **Prince Patel**

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#### EDUCATION:

### **Massachusetts Institute of Technology**

BS, Computer Science, Artificial Intelligence, and Mathematics, GPA: 4.7, SAT Math: 800, SAT Reading: 740

- Relevant Coursework: Real Analysis (18.100), Statistical Learning Theory (6.7910), Advanced Algorithms (6.1220), Computer Vision (6.8300), Statistics (18.650), Deep Learning (6.8898), Machine Learning (6.390),
  - Probability and Random Variables (18.600), Linear Algebra (18.06), Differential Equations (18.03)
- Organizations: South Asian Association of Students (Big Events Committee), Phi Kappa Theta (Risk Manager)

#### WORK EXPERIENCE:

#### Mind Company

Founding Engineer, ML Research

- Surpassed SOTA models by up to 10% on benchmarks for text, emotion, and motor intention decoding from non-invasive EEG recordings
- Developed a data collection web app for ~100 daily subjects, creating the largest labeled EEG dataset in 2 months
- Skills: PvTorch, deep learning, signal processing, system design, AWS, JavaScript, FastAPI

## Mach Industries

Software Engineer Intern

- Enhanced range on an autonomous glider plane by 10x by developing a flight controller in C++ using PID loops
- Engineered a 10-fold increase in displacement measurement accuracy by fusing a CNN-powered optical flow calculator with IMU readings and applying an EKF, overall improving VTOL hovering stability
- *Skills: C*++, *PyTorch*, *object-oriented programming*, *TypeScript*

### **Epicore Biosystems**

Data Science Intern

- Improved accuracy of a hydration-tracking wearable to 95% by implementing a generalized linear model for forecasting sweat rate with accelerometer and temperature data inputs
- Presented outcomes of implementing new predictive model to company executives and potential investors
- *Skills: TensorFlow, pandas, numpy, statistical analysis, data processing*

## **Biomechatronic Group, MIT Media Lab**

Undergraduate Researcher

- Predicting motor control of upper extremity amputees and translating to continuous prostheses control
- *Skills: PyTorch, pandas, numpy, computer vision, brain-computer interfaces*

## Marine Robotics Lab, MIT CSAIL

Undergraduate Researcher

- Trained a locomotion policy for a quadruped robot in Isaac Gym using a PPO reinforcement learning program
- *Skills: PyTorch, C/C++, reinforcement learning, robotics, computer vision*

## EXTRACURRICULAR EXPERIENCE:

## **MIT Class Council**

Vice President

Expanding the impact of class-wide initiatives by collaborating with campus organizations to forge partnerships -

## **MIT Capital Partners**

Sourcing Principal

- Demonstrated expertise in analyzing industry trends, competitive landscapes, and growth potential of startups
- Employed strong communication skills to establish mutually beneficial partnerships with startups and VC clients -

## **PROJECTS**:

# Multimodal Embeddings for High-Fidelity Image Compression

- Outperformed SOTA methods by 12% using a unique process of image segmentation and LLM captioning for encoding and a multimodal diffusion model for decoding
- Achieved 80% compression rate while reconstructing images with <5% loss in visual quality scores

# **Denoising EMG Signals**

Reduced noise in raw sEMG data by 300% by developing and training a denoising autoencoder model with self-attention in the encoder. Communicated findings via a scientific blog post.

Mar. 2023 – Dec. 2023

June 2023 – Sep. 2023

Dec. 2022 – Apr. 2023

Mar. 2023 – Present

*Mar.* 2023 – Present

May 2024

Dec. 2023

May 2024 - Pesent

Jan. 2024

Expected 2026